

An Optimal Distributed Discrete Log Protocol with Applications to Homomorphic Secret Sharing

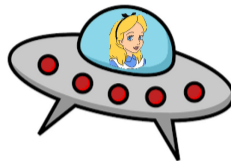
Itai Dinur¹, **Nathan Keller**² and **Ohad Klein**²

¹ Department of Computer Science, Ben-Gurion University, Israel

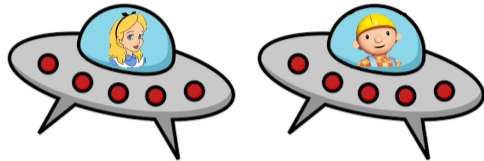
² Department of Mathematics, Bar-Ilan University, Israel

August 22, 2018

The Spaceships Problem

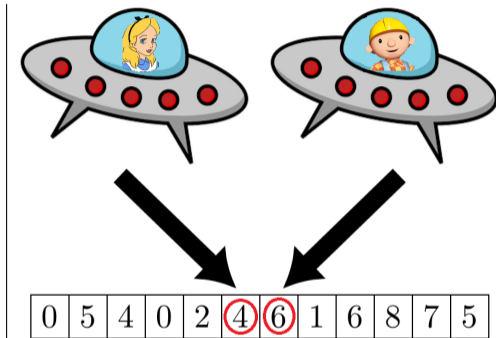


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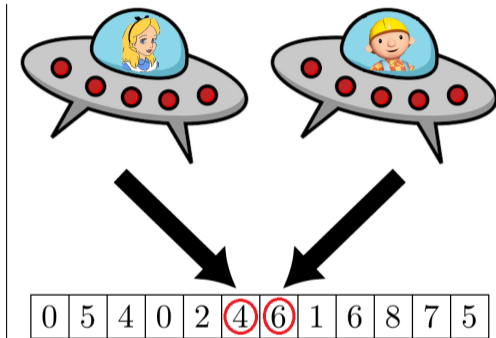
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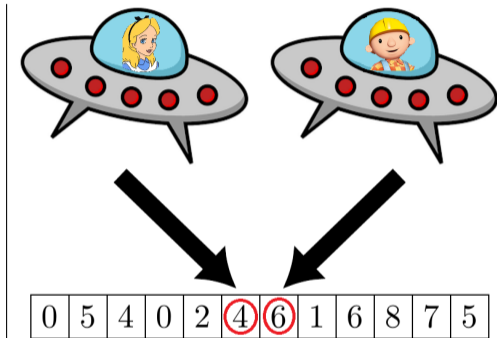
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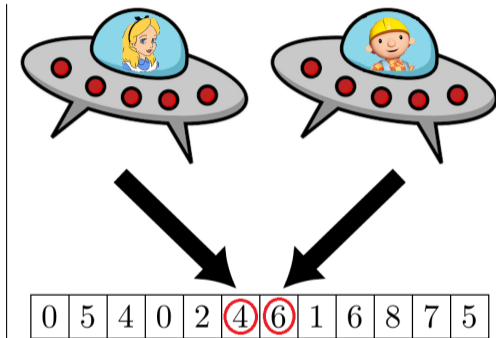
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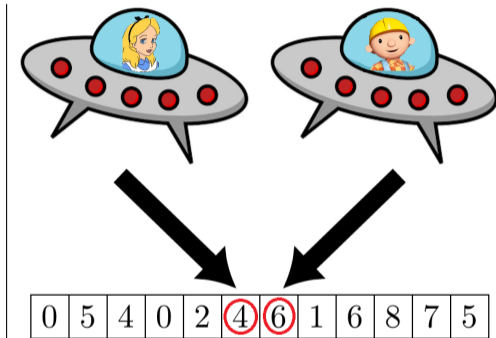
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Main Problem

- How can the spaceships maximize their meeting probability?
- What is this highest probability (depending on T)?

Algorithm: Basic

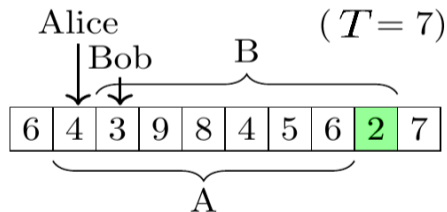
```
1: function BASIC(array, start, T)  
2:   return arg mini ∈ [start, start + T) {array[i]};
```

Basic algorithm

Algorithm: Basic

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 - 2: **return** $\arg \min_{i \in [start, start+T)} \{array[i]\};$
-

Analysis



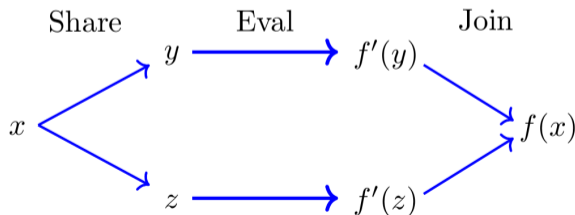
Alice & Bob fail to synchronize iff minimum is on one of the ends.
Probability = $2/(T + 1)$.

Homomorphic Secret Sharing

- **Homomorphic Secret Sharing** – introduced by Boyle, Gilboa, Ishai [**BGI**] (CRYPTO'16) as a more practical alternative to **FHE** (Fully-Homomorphic-Encryption).
- Suppose we wish to securely compute in the cloud.
- HSS enables to distribute the evaluation of a **public function** f on a **secret input** x among two servers, each receiving a secret share y or z , so that $f(x)$ can easily be recovered from $f'(y)$ and $f'(z)$.

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- HSS enables to distribute the evaluation of a **public function** f on a **secret input** x among two servers, each receiving a secret share y or z , so that $f(x)$ can easily be recovered from $f'(y)$ and $f'(z)$.
 - Each of y and z computationally hides x .



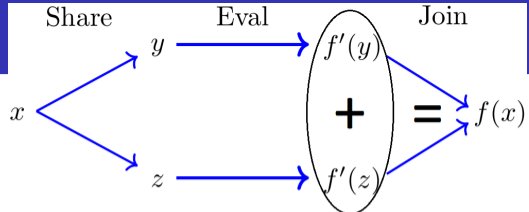
- 'Share' and 'Join' are cheap.

- BGI constructed a group based HSS protocol.
 - Security Relies **only on DDH** (Decisional-Diffie-Hellman) Hardness assumption.
 - **Low communication complexity**.
 - **Applicable only for** functions f inside the class of '**branching programs**'.

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 - **PIR**: Private information retrieval (with branching program predicate).
 - **SMPC**: Secure multi-party computation in sublinear communication (leveled circuits).

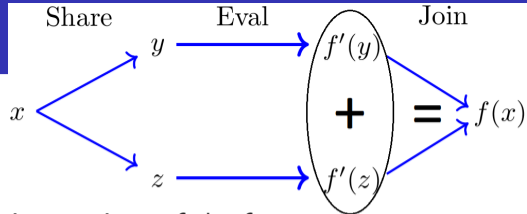
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- Applications
 - **PIR**: Private information retrieval (with branching program predicate).
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- Requires an algorithm solving the Distributed-Discrete-Log problem (**DDLOG**).

Overview of BGI's HSS Protocol (1)



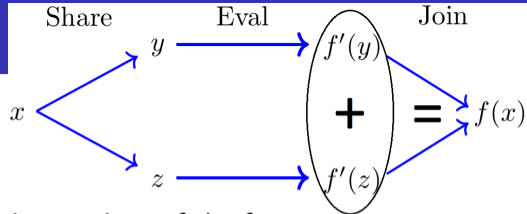
- Let $x = (x_1, \dots, x_n) \in \{0, 1\}^n$ be a secret input.
- We wish to compute $f(x) \in \mathbb{Z}$, where f contains instructions of the form:
 - 1) $v_i \leftarrow v_j \pm v_k$ for variables $v_i, v_j, v_k \in \mathbb{Z}$.
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- SHARE x :
 - Let \mathbb{G} be a cryptographic group generated by g .
 - Choose random y_i, z_i with $x_i = y_i + z_i$, and **share** $\mathbf{y}_i, \mathbf{z}_i$ respectively.
 - Also, **publish** \mathbf{g}^{x_i} . (Actually, use something similar to El-Gamal.)

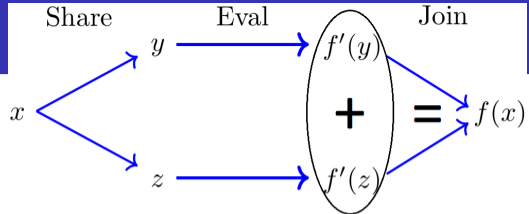
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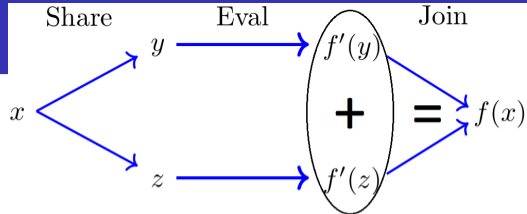
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- Evaluation of \mathbf{f}' almost **identical to evaluation of \mathbf{f}** .
- We maintain that at any time t , $\mathbf{v}_i^t(\mathbf{x}) = \mathbf{v}_i^t(\mathbf{y}) + \mathbf{v}_i^t(\mathbf{z})$.
 - Trivial for instructions 1 & 3. What about 2?

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- How would we implement $v_i \leftarrow v_j \cdot x_k$?
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- We seek for an **efficient** probabilistic algorithm $A: \mathbb{G} \rightarrow \mathbb{Z}/|\mathbb{G}|$ satisfying:

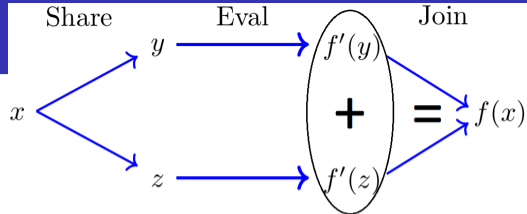
Simplified DDLOG problem

Let $u, v \in \{0, 1\}$, then

$$\Pr [A(g^u) + A(g^v) \neq u + v] \leq \delta,$$

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- Can binary expand v_j and assume $v_j \in \{0, 1\}$.
- Degenerate formulation due to usage $t \mapsto g^t$, instead of El-Gamal.

DDLOG problem

Let \mathbb{G} be a cyclic cryptographic group, with a generator g .

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DDLOG & Spaceships problems

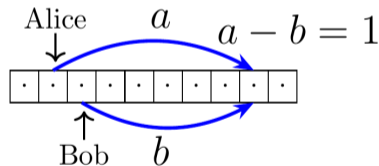
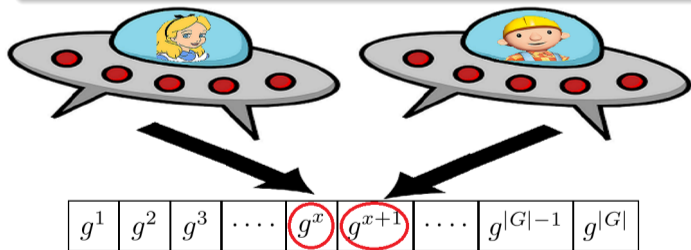
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- Apply a PRF on g^t to randomize.

- BGI used 'Basic' algorithm, achieving $\delta = 1/T$ for running time $O(T)$.

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Results

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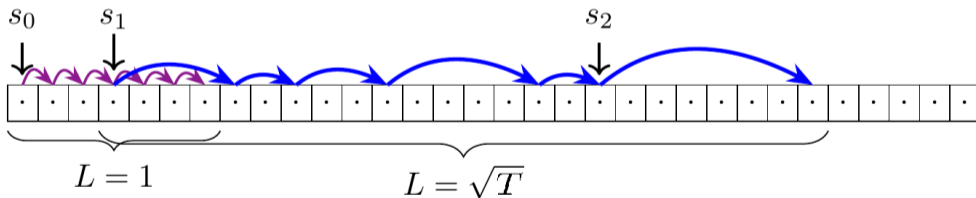
Algorithm is optimal in groups satisfying the DLI-Hardness assumption.

Optimal Algorithm

- Algorithm is composed of several 'jumping' phases.
- The 'Jump' algorithm is a variant of Pollard's kangaroo algorithm.

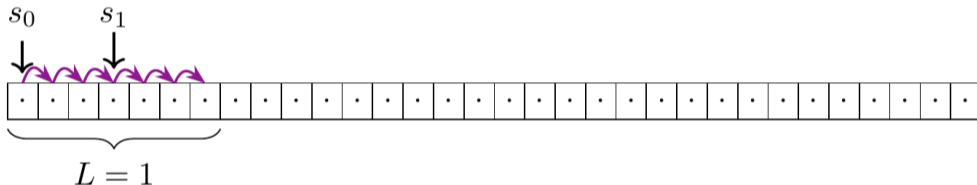
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- We view a 2-staged algorithm, achieving $O(1/T^{3/2})$ error, with T queries.



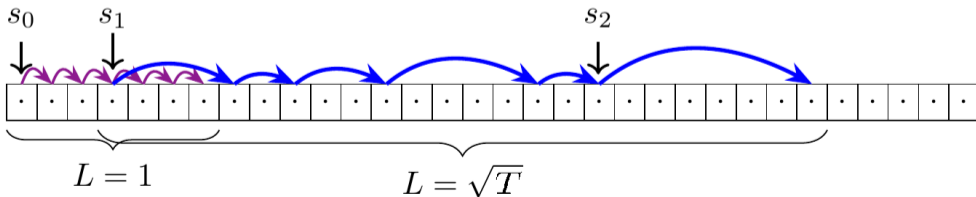
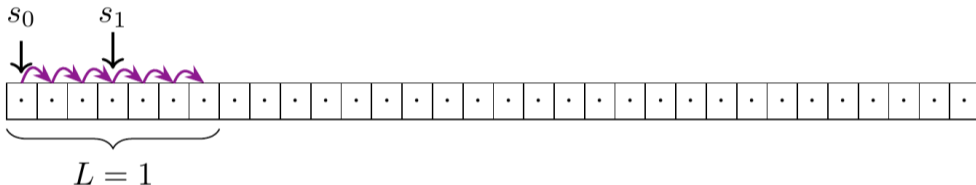
2 staged algorithm

- Phase 1 is just 'Basic' algorithm with $T/2$ steps.

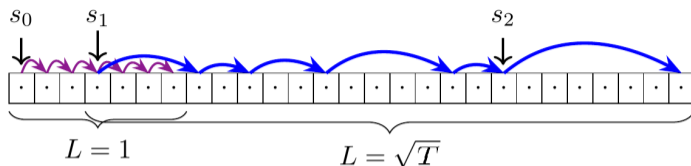


2 staged algorithm

- Phase 1 is just 'Basic' algorithm with $T/2$ steps.
- Phase 2 performs $T/2$ jumps of size $\sim U(1, \sqrt{T})$ depending on current location.
- Phase 2 starts from minimum of phase 1; stops at its own minimum.

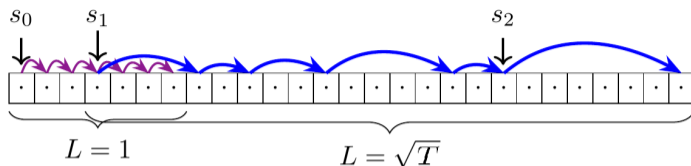


Analysis of algorithm



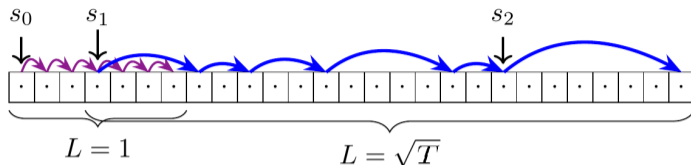
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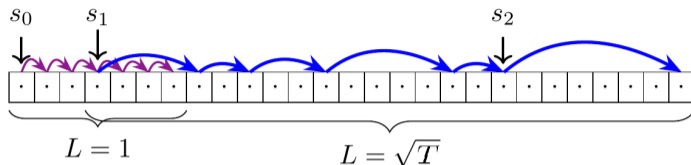
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- On second stage, parties make $T/2$ steps of size $\leq L = \sqrt{T}$, their random walks are expected to meet after $\mathbf{O}(\sqrt{T})$ steps.
- Thus, walks share $T - O(\sqrt{T})$ steps \Rightarrow fail with prob. $\mathbf{O}(\sqrt{T}/T)$.

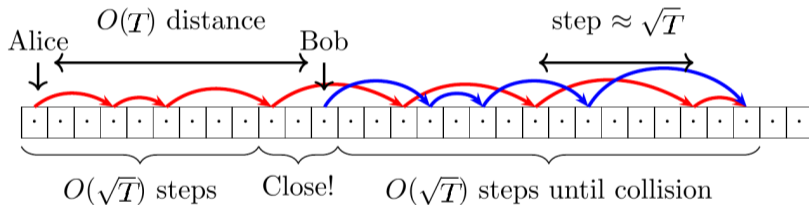
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- \Downarrow
- After second stage, synchronized except for probability $\mathbf{O}(T^{-3/2})!$

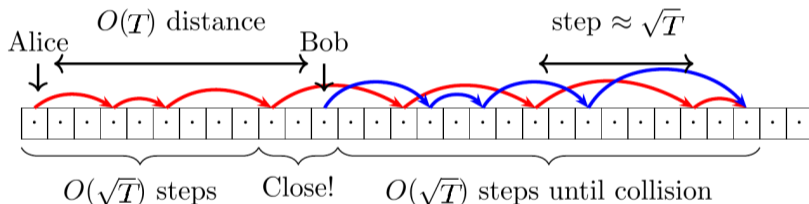
Analysis of algorithm

- Why would two random walks, starting $O(T)$ apart, with step-size $O(\sqrt{T})$, collide after $O(\sqrt{T})$ steps?



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- In general, if distance $\sim D$, and step size $\sim L$, collision after $\sim D/L + L$ steps.
 - Choose $L = \sqrt{D}$ to minimize collision time.

Summary

In case Alice and Bob start with distance 1 apart, they can meet except for probability $O(1/T^2)$, by reading T cells.

- What if their initial distance is M ?

Distant Alice & Bob

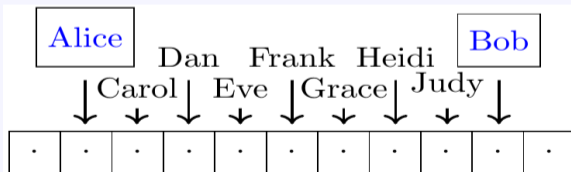
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Answer

By using the same algorithm, they meet except for probability $O(M/T^2)$.



$$\Pr[f(A) \neq f(B)] \leq \Pr[f(A) \neq f(C)] + \dots + \Pr[f(J) \neq f(B)]$$

Lower Bound on DDLOG (assuming DLI)

Discrete-Log-in-Interval Hardness assumption

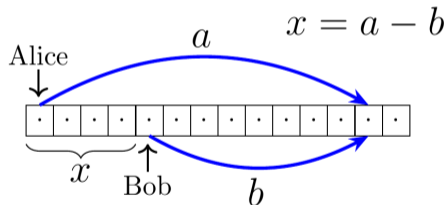
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No algorithm can find x , given g^x , in time $o(\sqrt{R})$, assuming $x \sim U(0, R)$.

- Spaceships algorithm solves DLI in $O(\sqrt{R})$.
 - Land Alice & Bob on the array $\text{arr}[t] = g^t$.
 - Put Alice at g^0 , and Bob at g^x .
 - Let them perform $O(2\sqrt{R})$ queries.
 - Finds DLOG except for prob. $x/(2\sqrt{R})^2 < 1/2$.



- Hence optimal!
- Solution for the spaceships problem can truly be proved to be optimal up to constant factors.

- The Distributed Discrete Log Problem.
- Application to HSS.
- An optimal algorithm solving DDLOG. (Improving $O(1/T)$ to $O(1/T^2)$)
- A formal analysis of the algorithm is in the paper.
- A matching lower bound assuming DLI hardness assumption.

Techniques

- Iterated variant of **Pollard's Kangaroo** algorithm.
- Analysis of algorithm with **Martingales**.
- Lower bounds with **Discrete Fourier Analysis**.

Thank You!

Algorithm: Optimal

```
1: function OPTIMAL(arr, start, T)
2:   s = JUMP(arr, start, T, 1);
3:   s = JUMP(arr, s, T,  $T^{1/2}$ );
4:   s = JUMP(arr, s, T,  $T^{3/4}$ );
5:   s = JUMP(arr, s, T,  $T^{7/8}$ );
6:    $\vdots$     $\vdots$     $\vdots$     $\vdots$ 
7:   return s;
```

Algorithm: Jump

```
1: function JUMP(arr, s, T, L)
2:   i, min = s, s;
3:   repeat T times
4:     if arr[i] < arr[min] then
5:       mini = i;
6:     i += 1 + Hash(arr[i])%L;
7:   return min;
```
